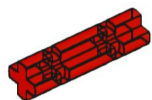


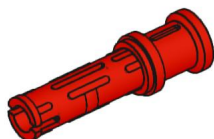
4x



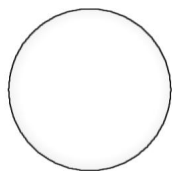
3x



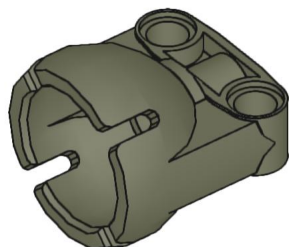
18x



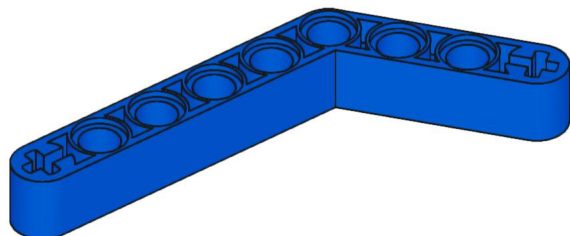
4x



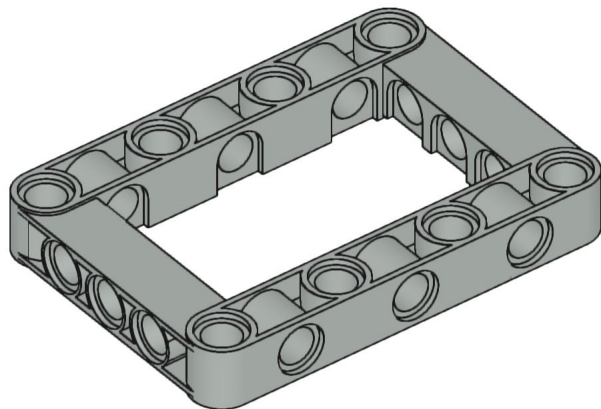
1x



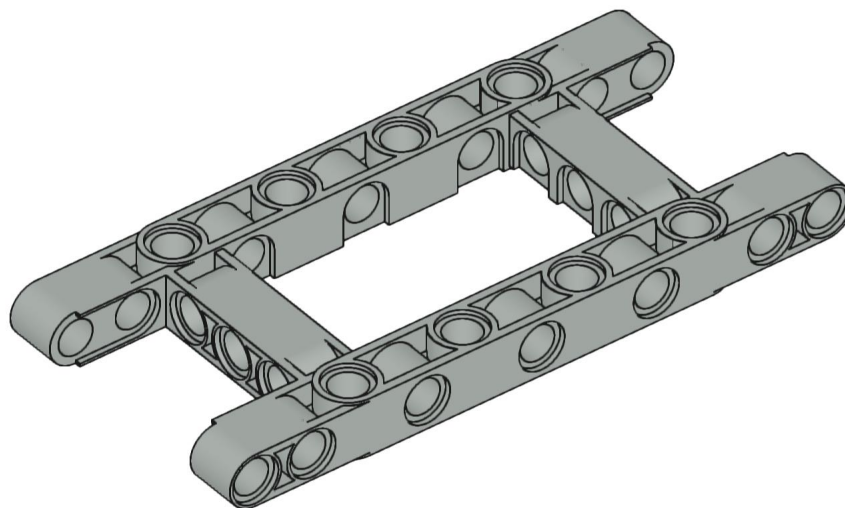
1x



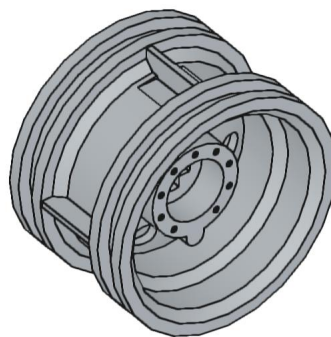
1x



1x



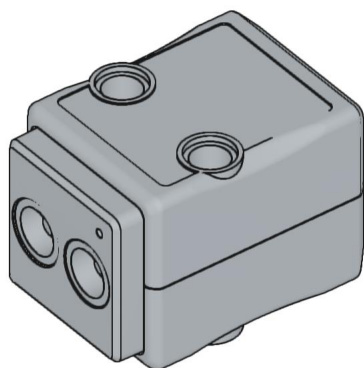
3x



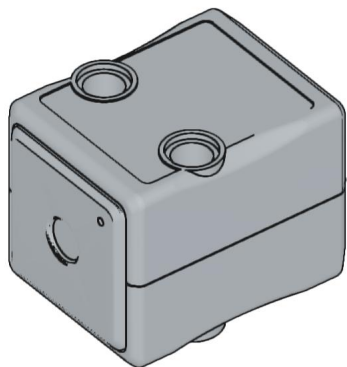
2x



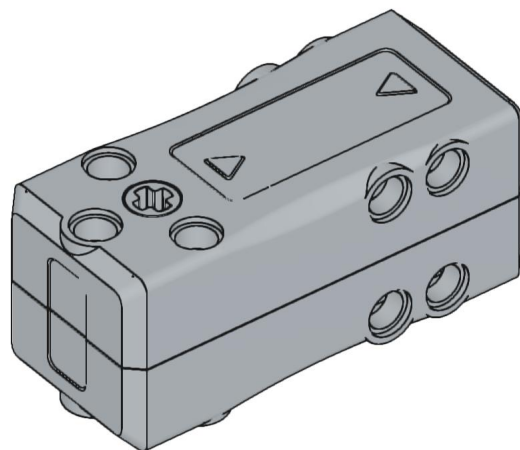
**2x**



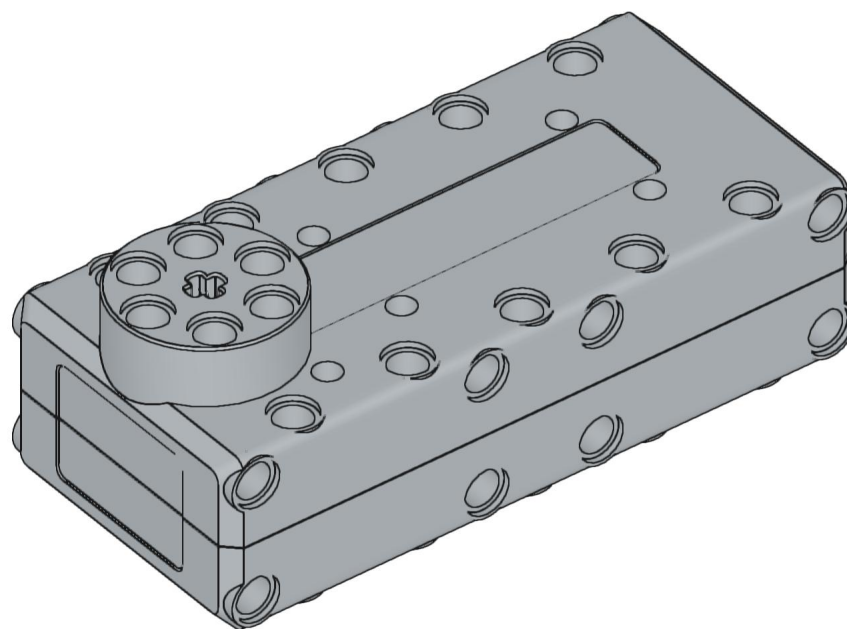
**1x**



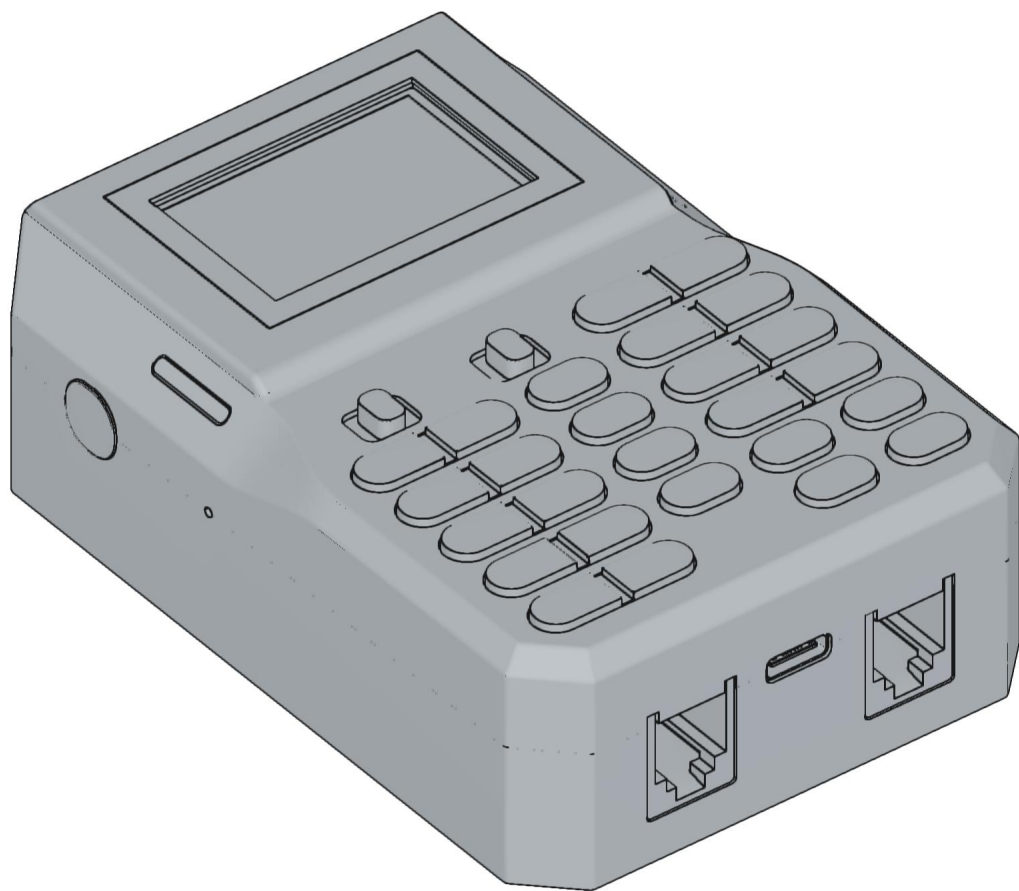
**1x**



**1x**

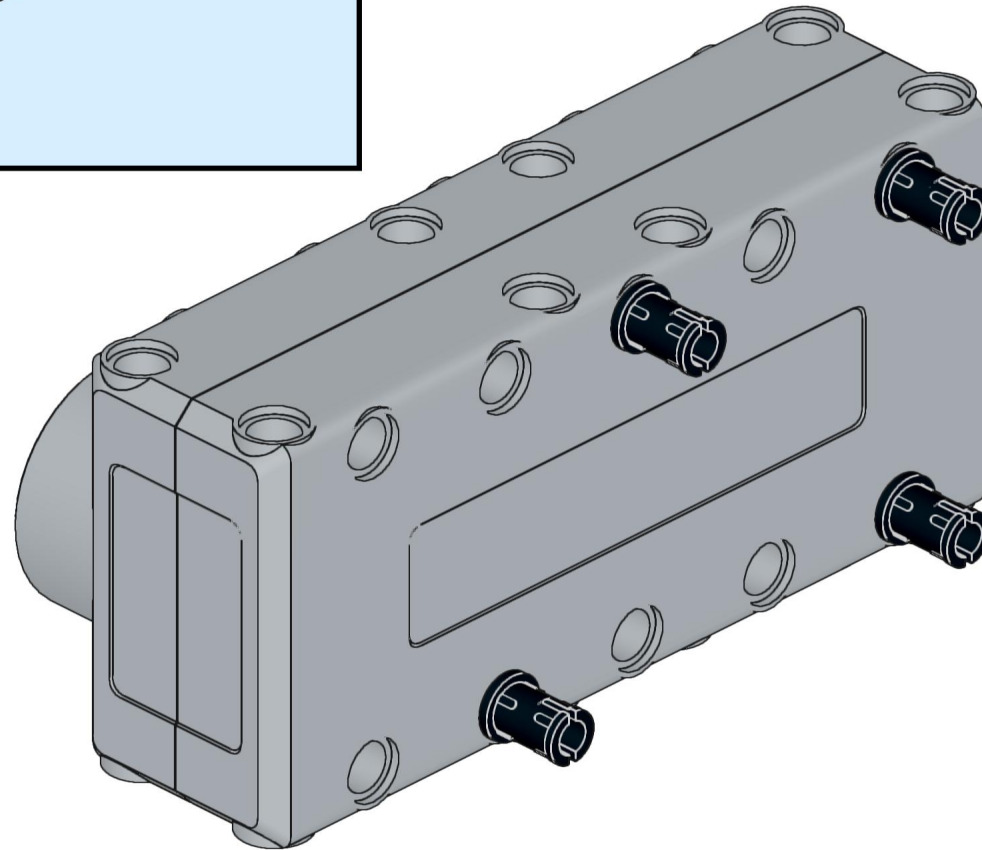
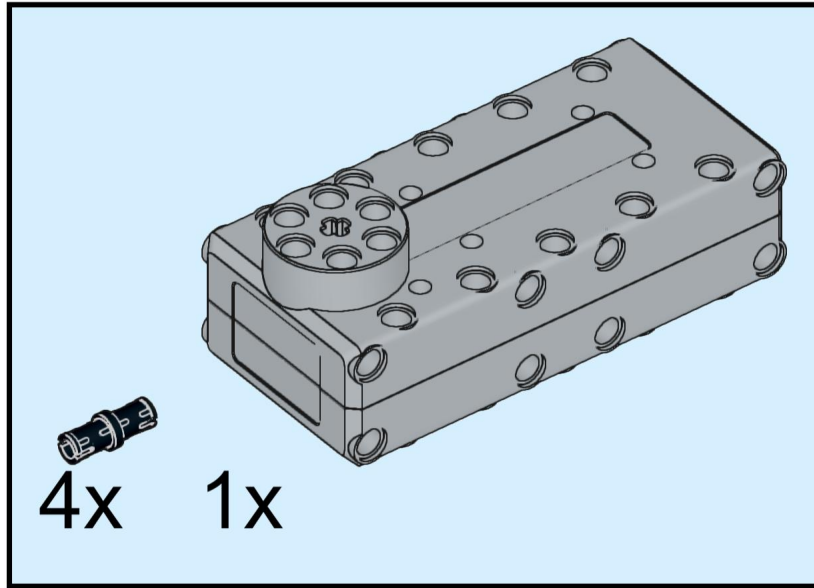


**2x**

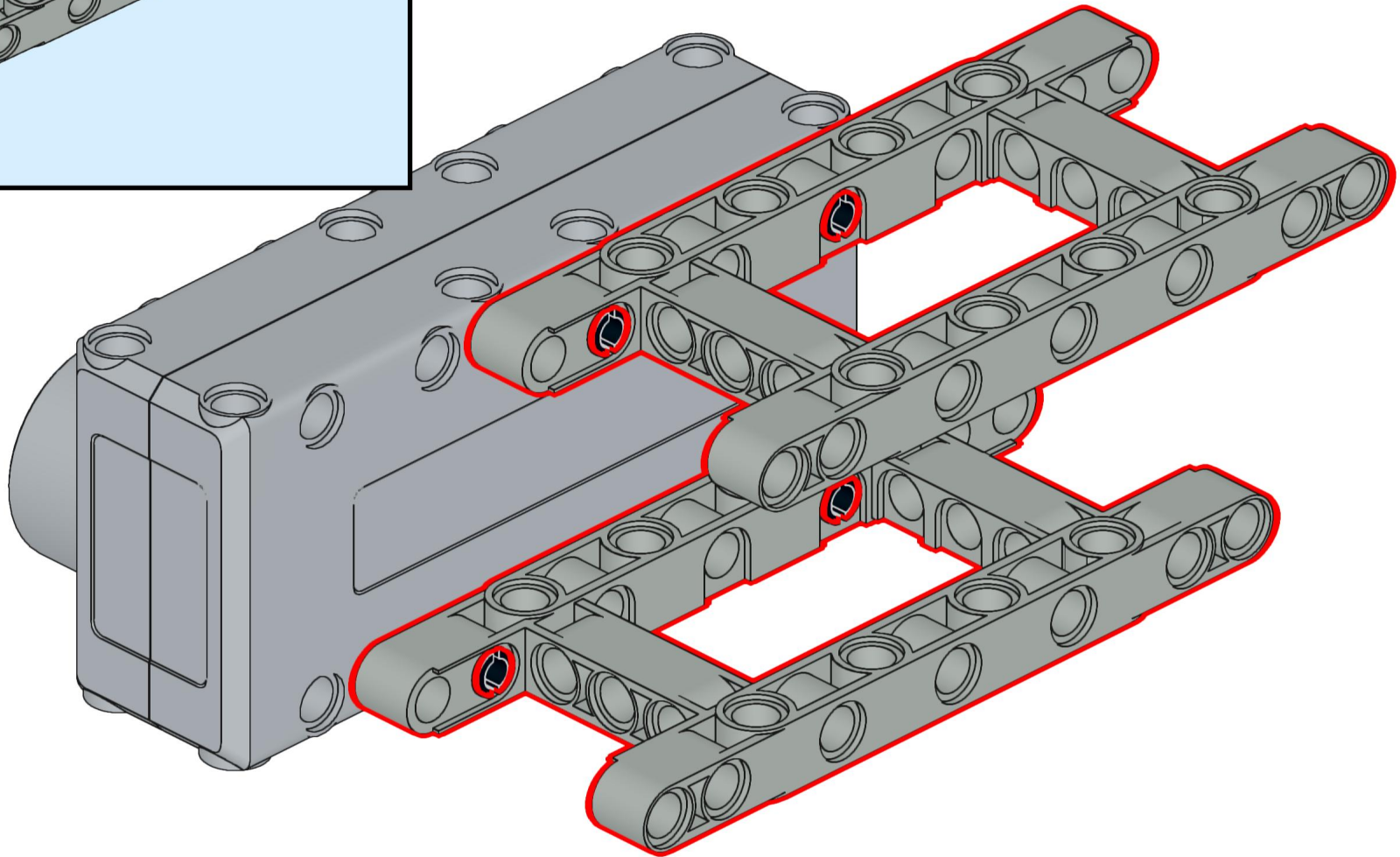
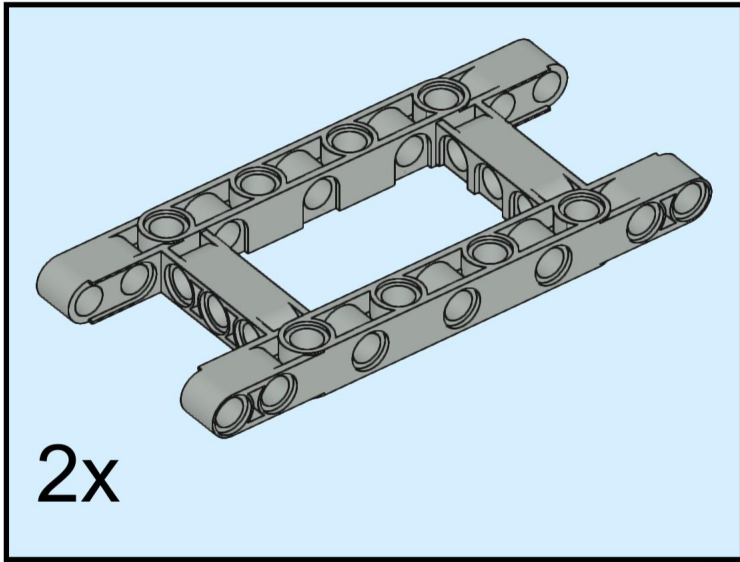


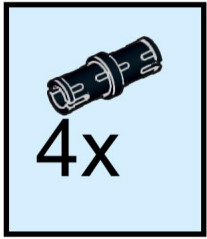
**1x**

1

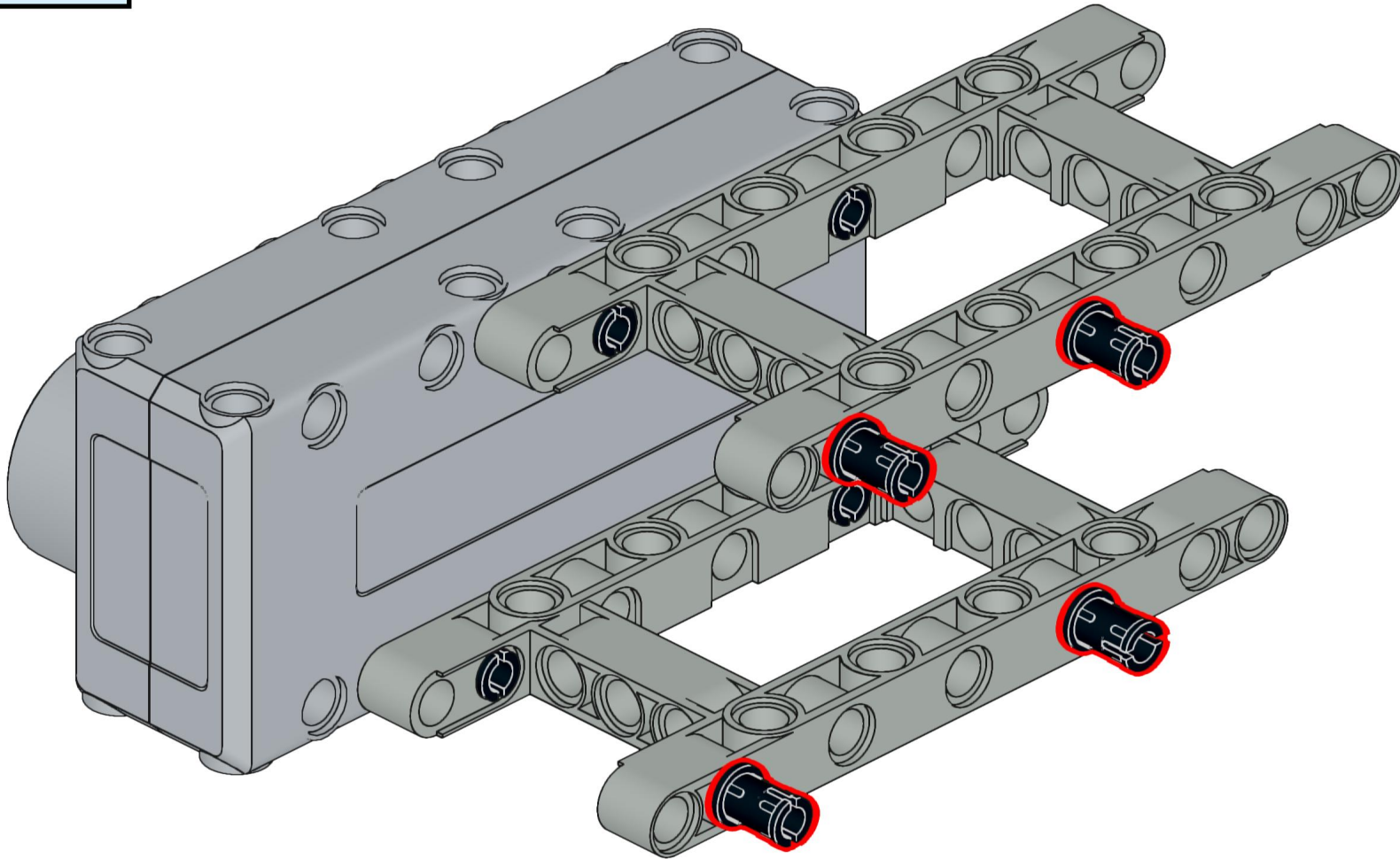


2

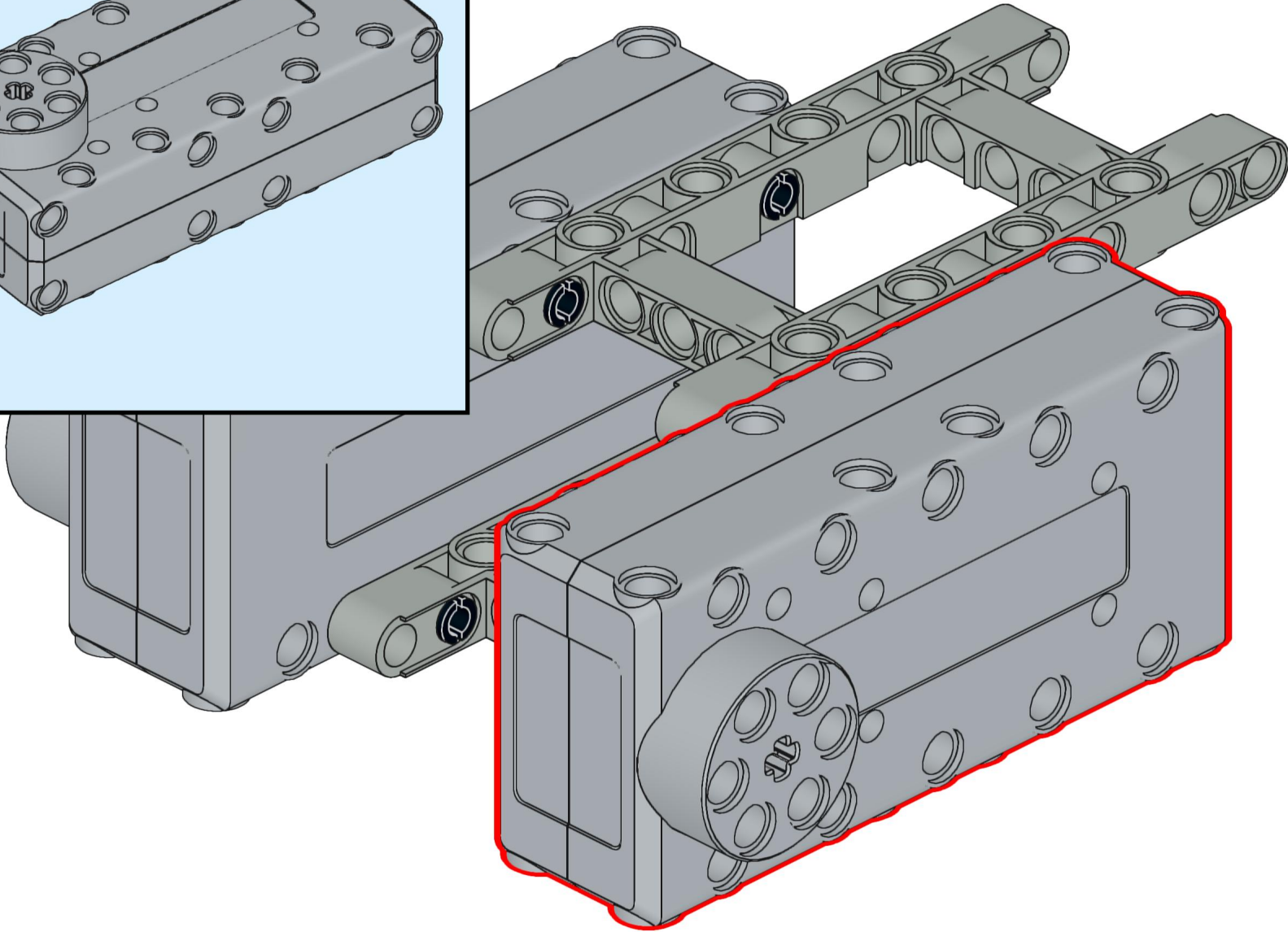
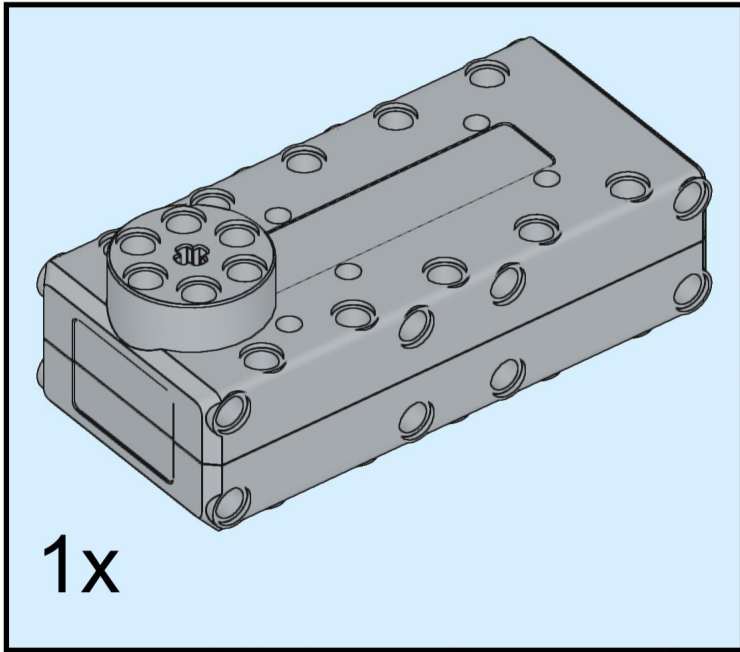


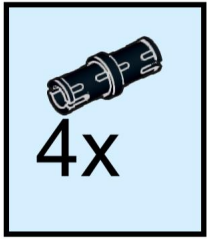


3

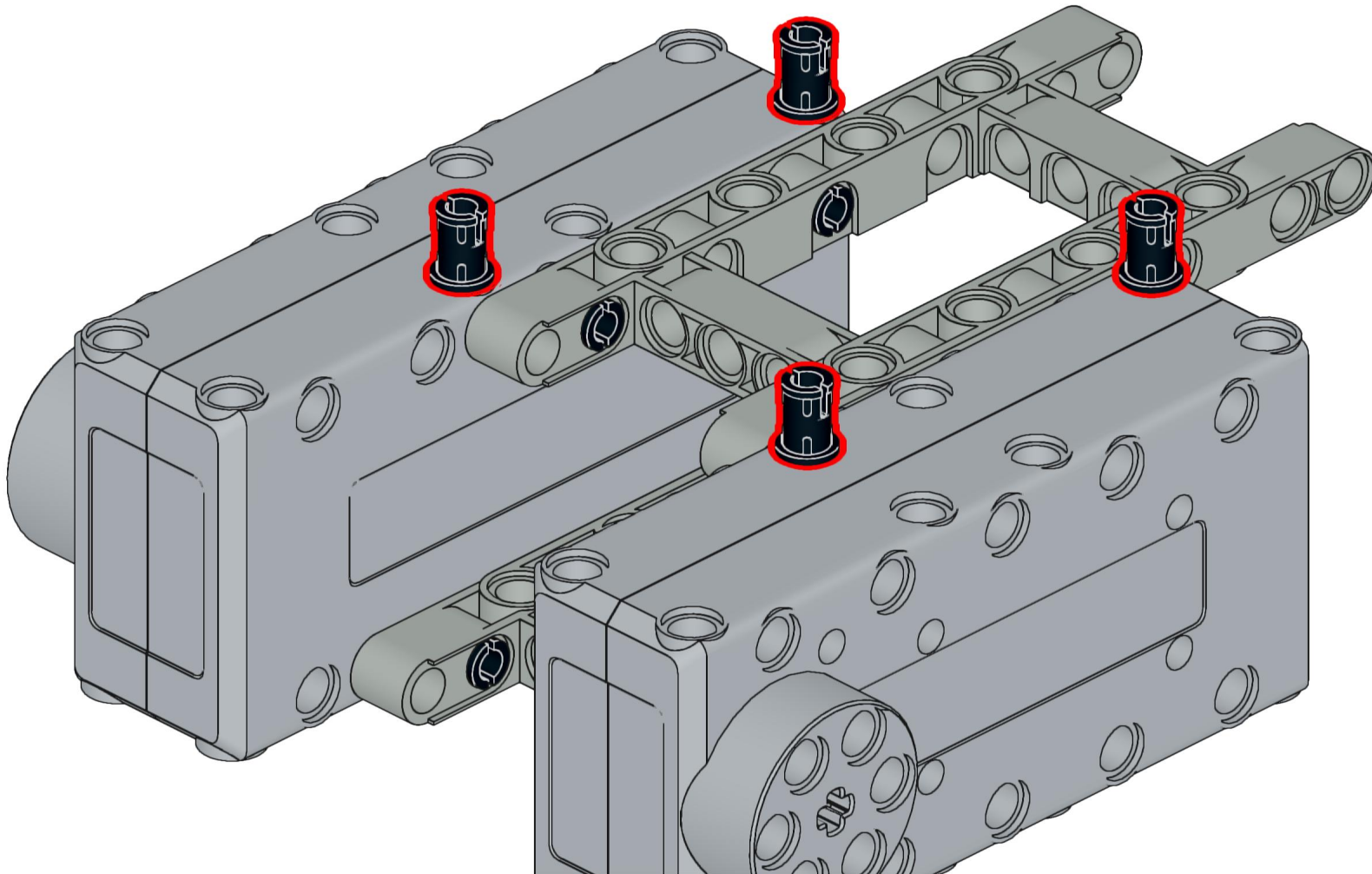


4

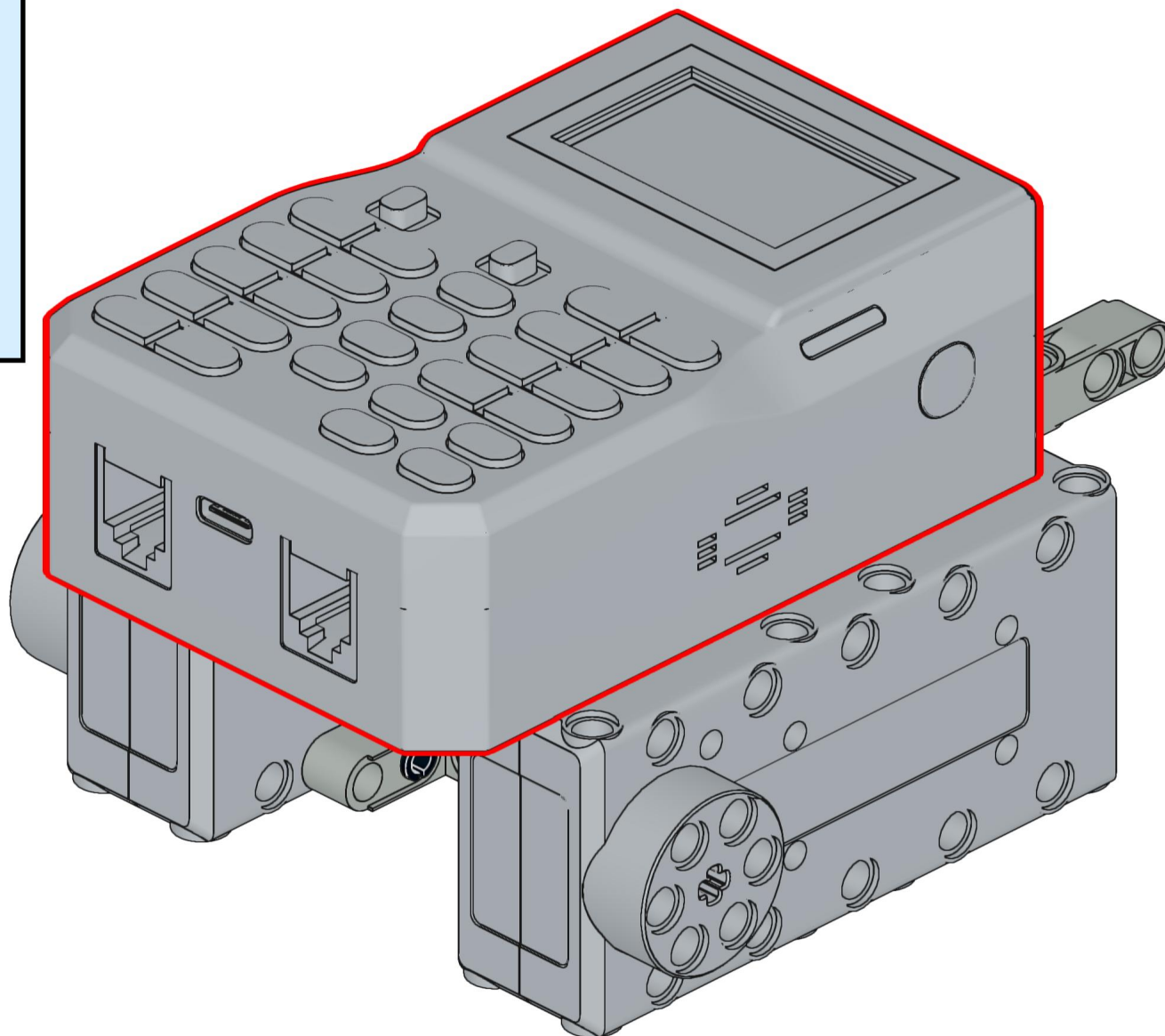
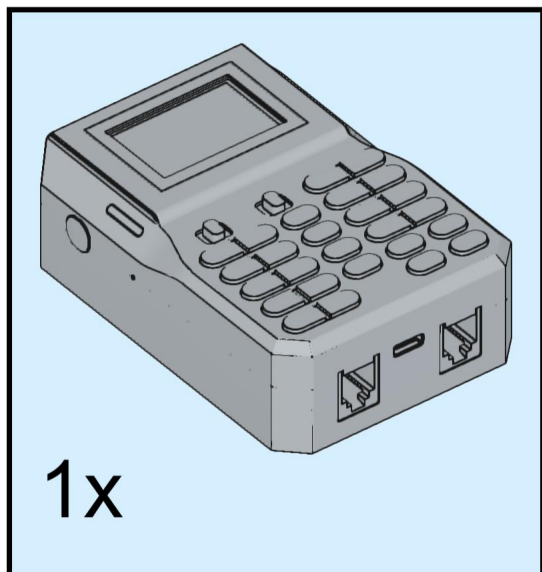


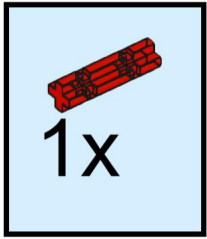


5

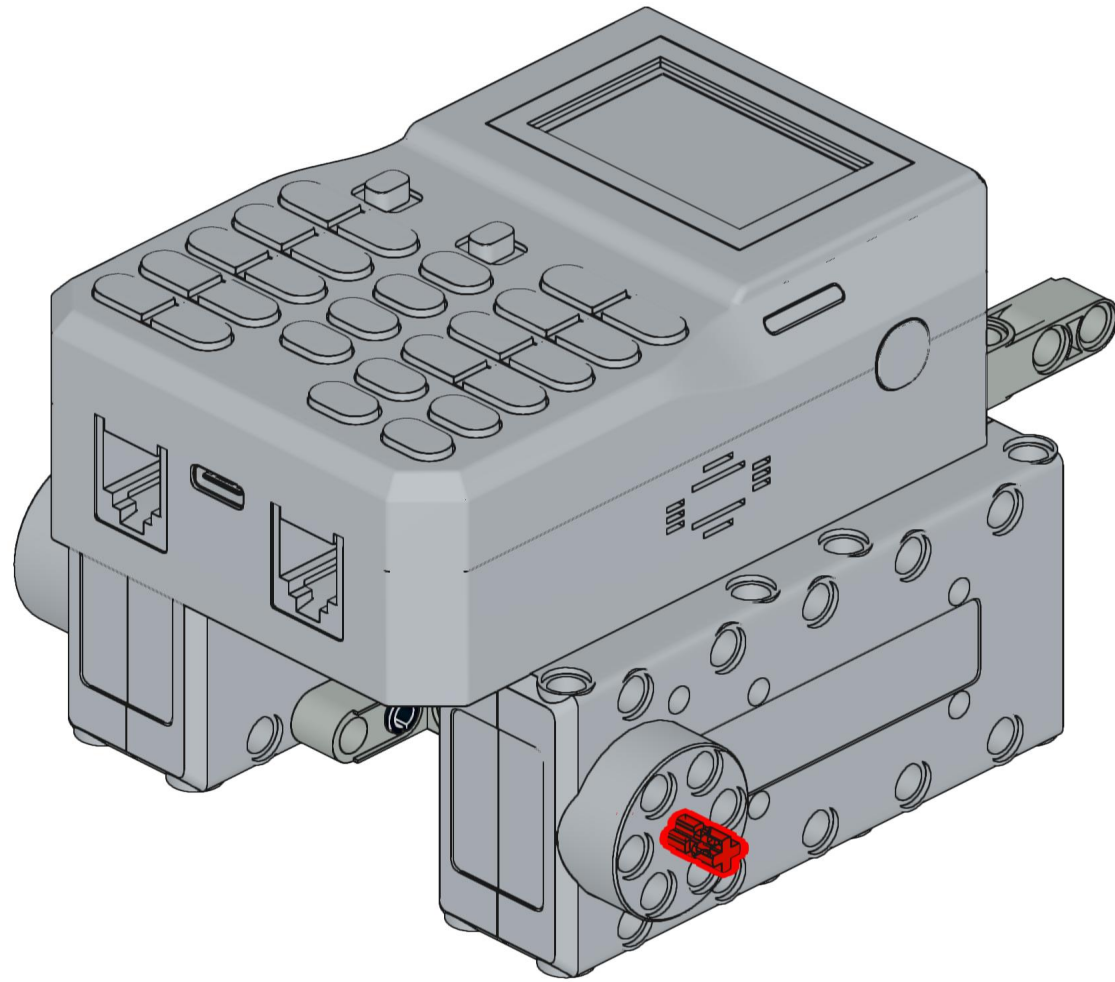


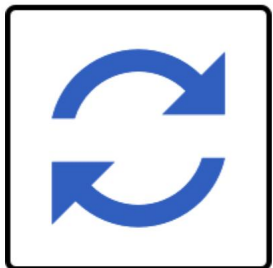
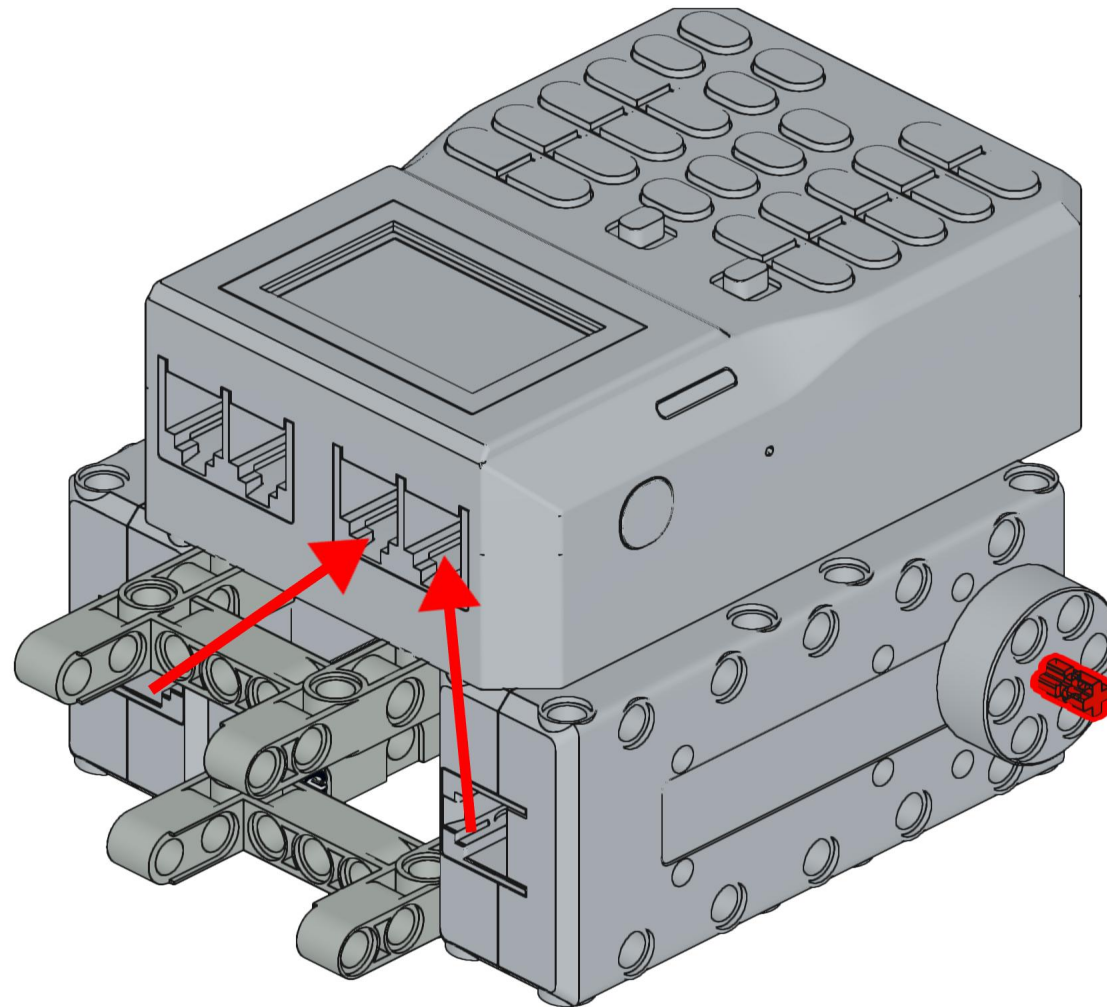
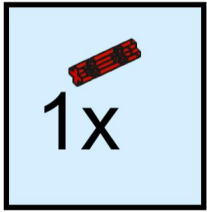
6



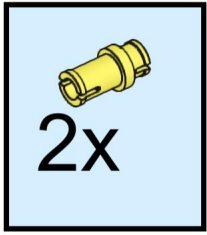


7

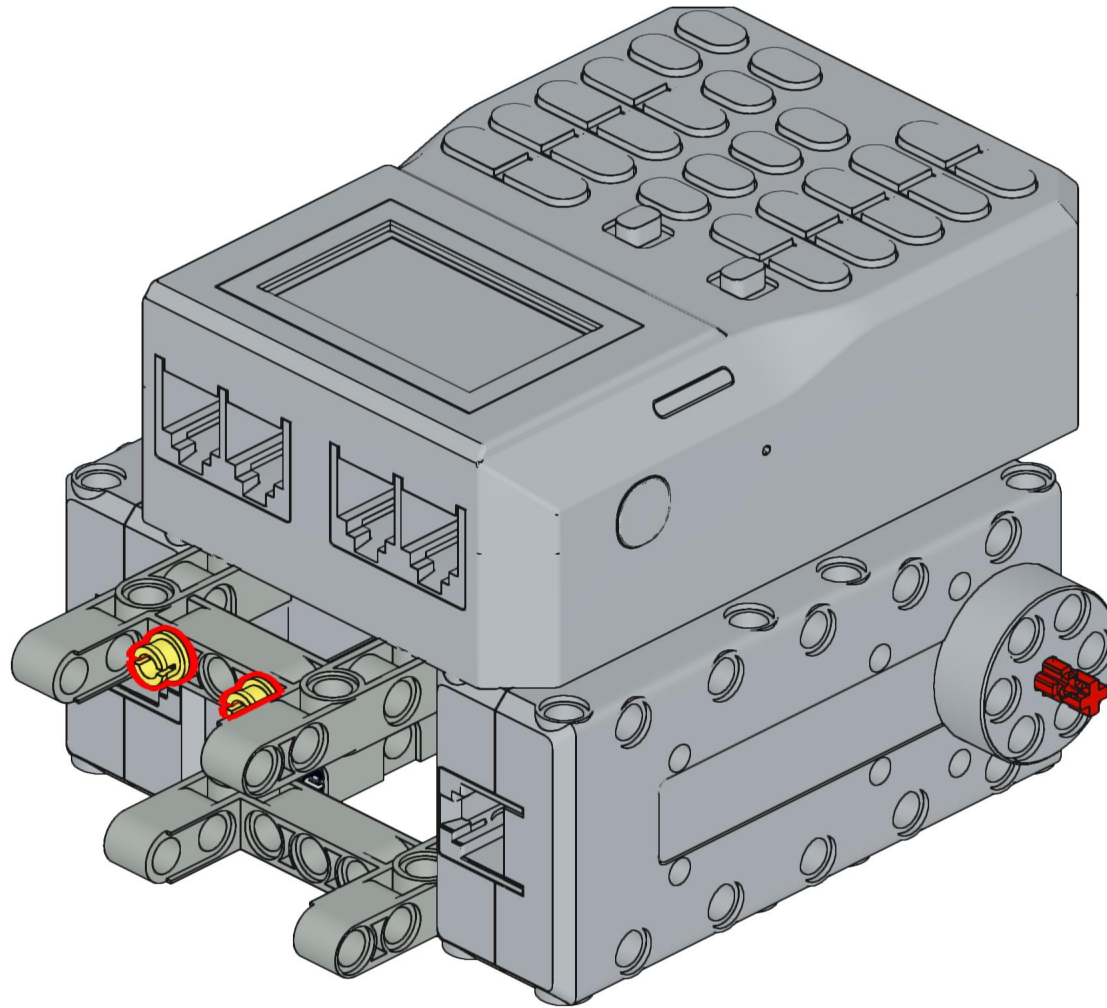




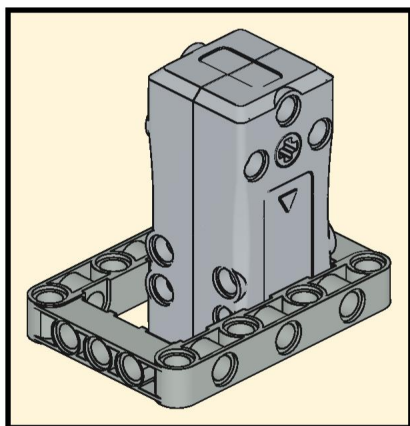
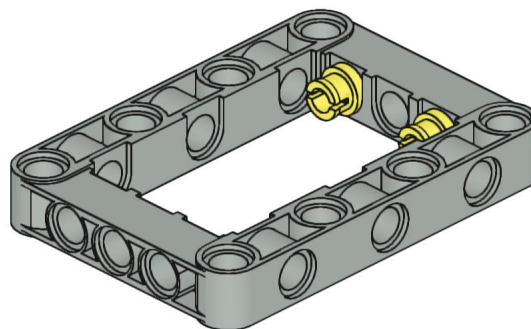
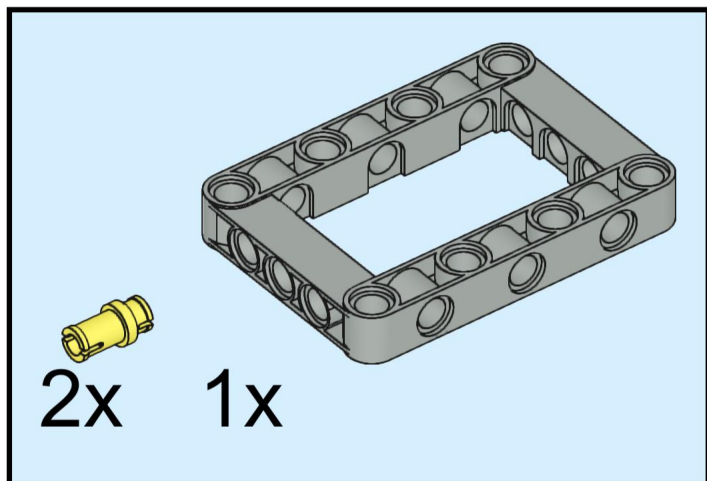
Two motors are connected as shown in the figure.

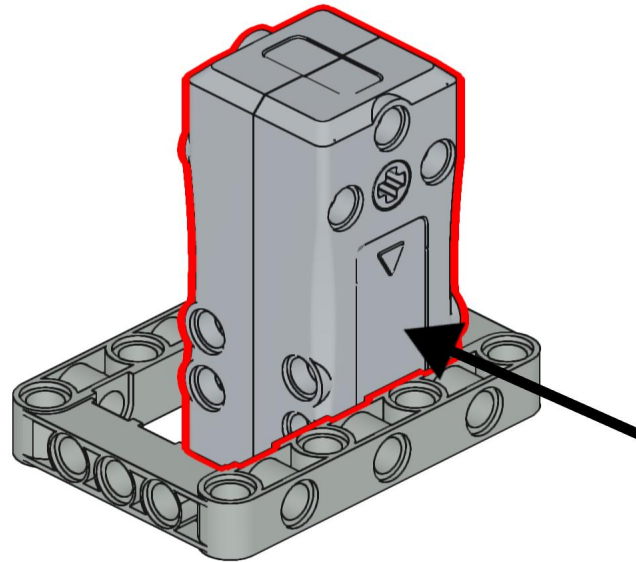
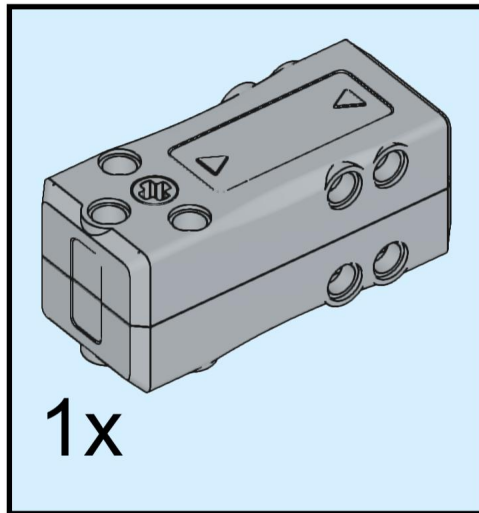


9



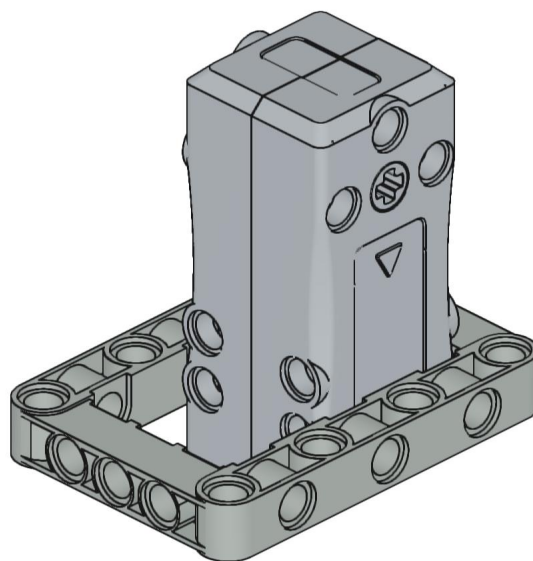
# 10



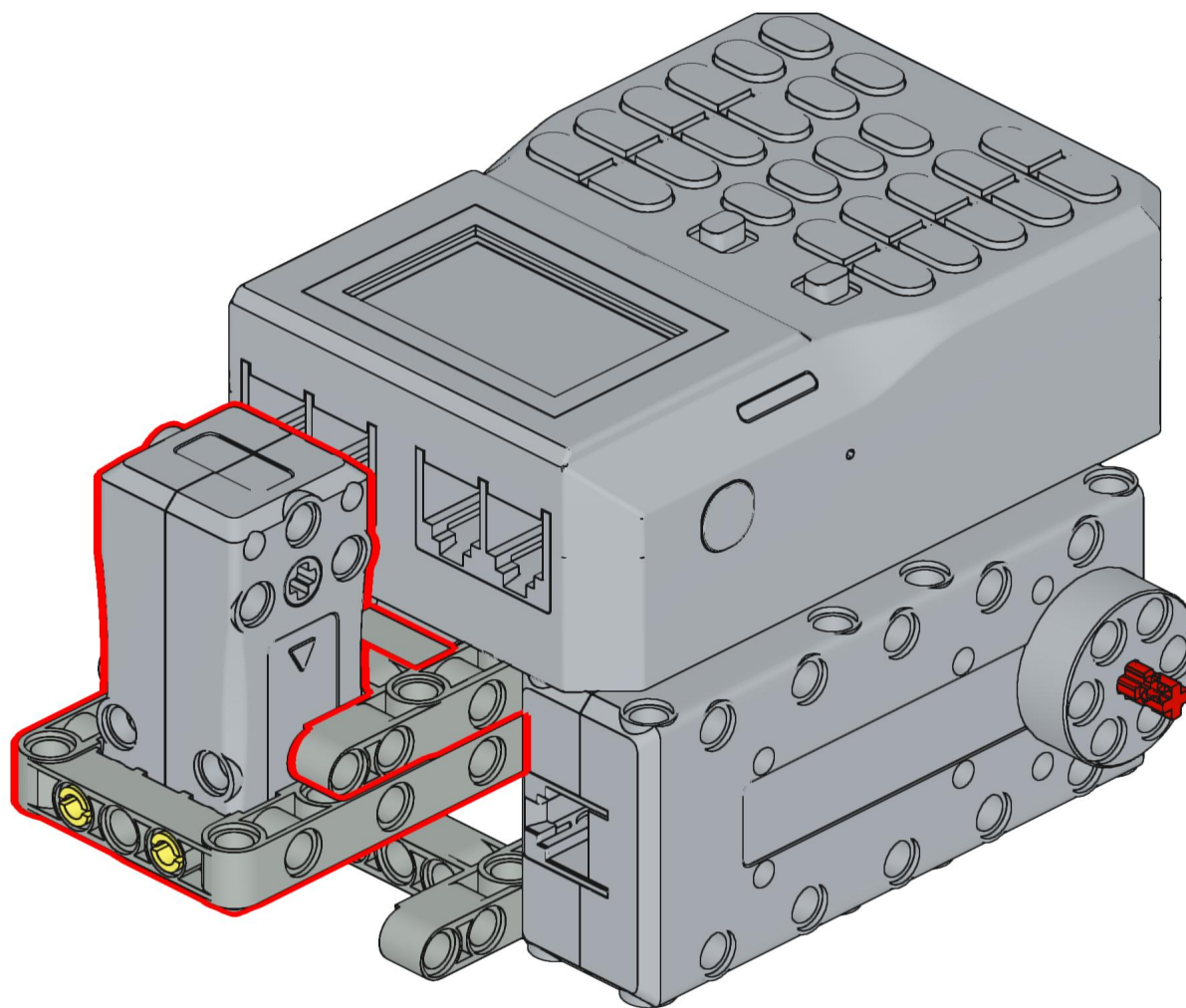


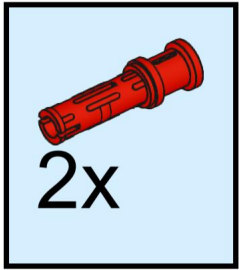
This side has the word "servo motor" on it.

# 12

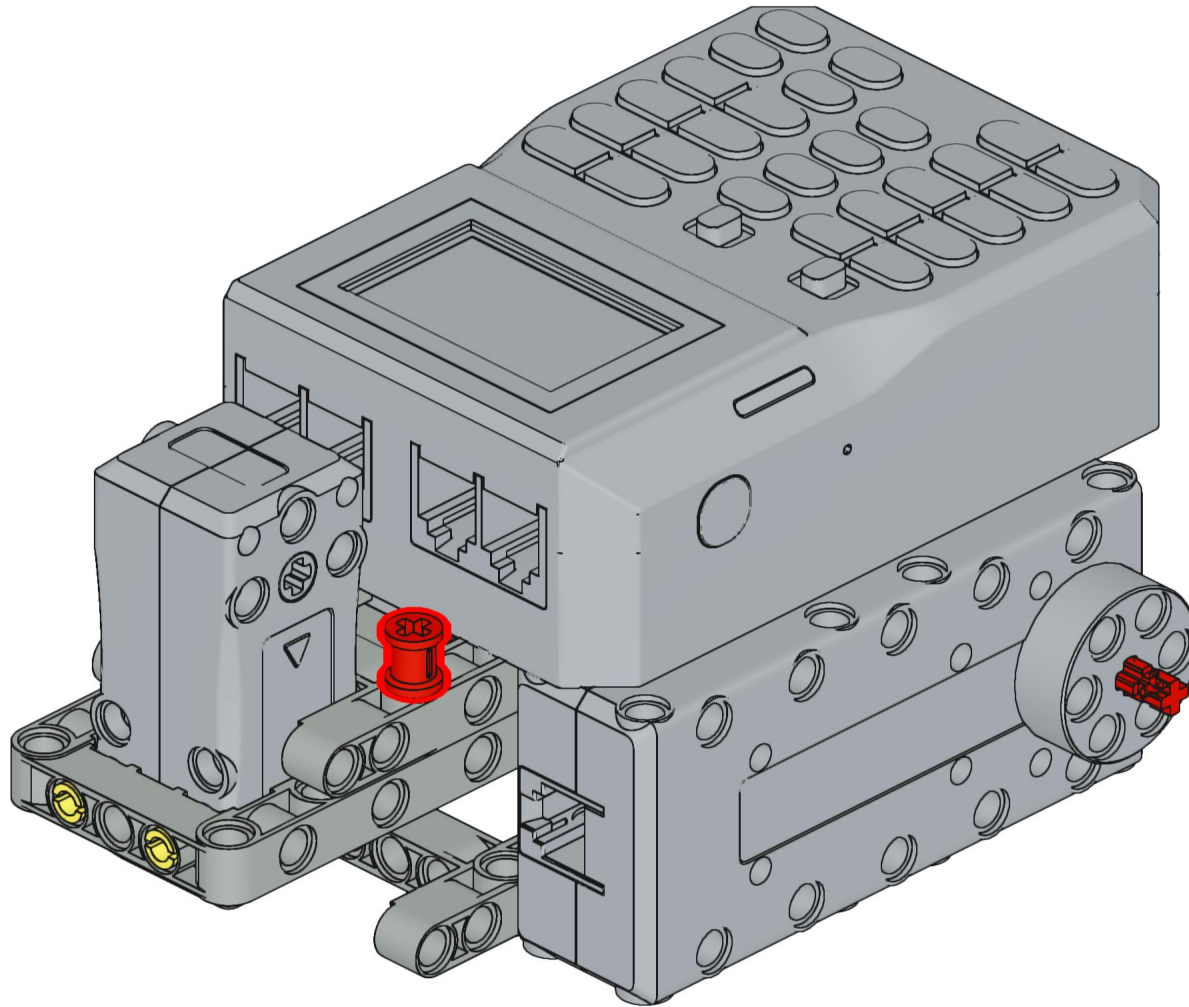


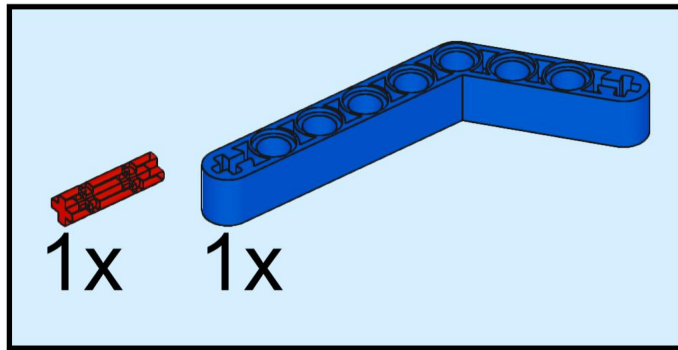
# 13



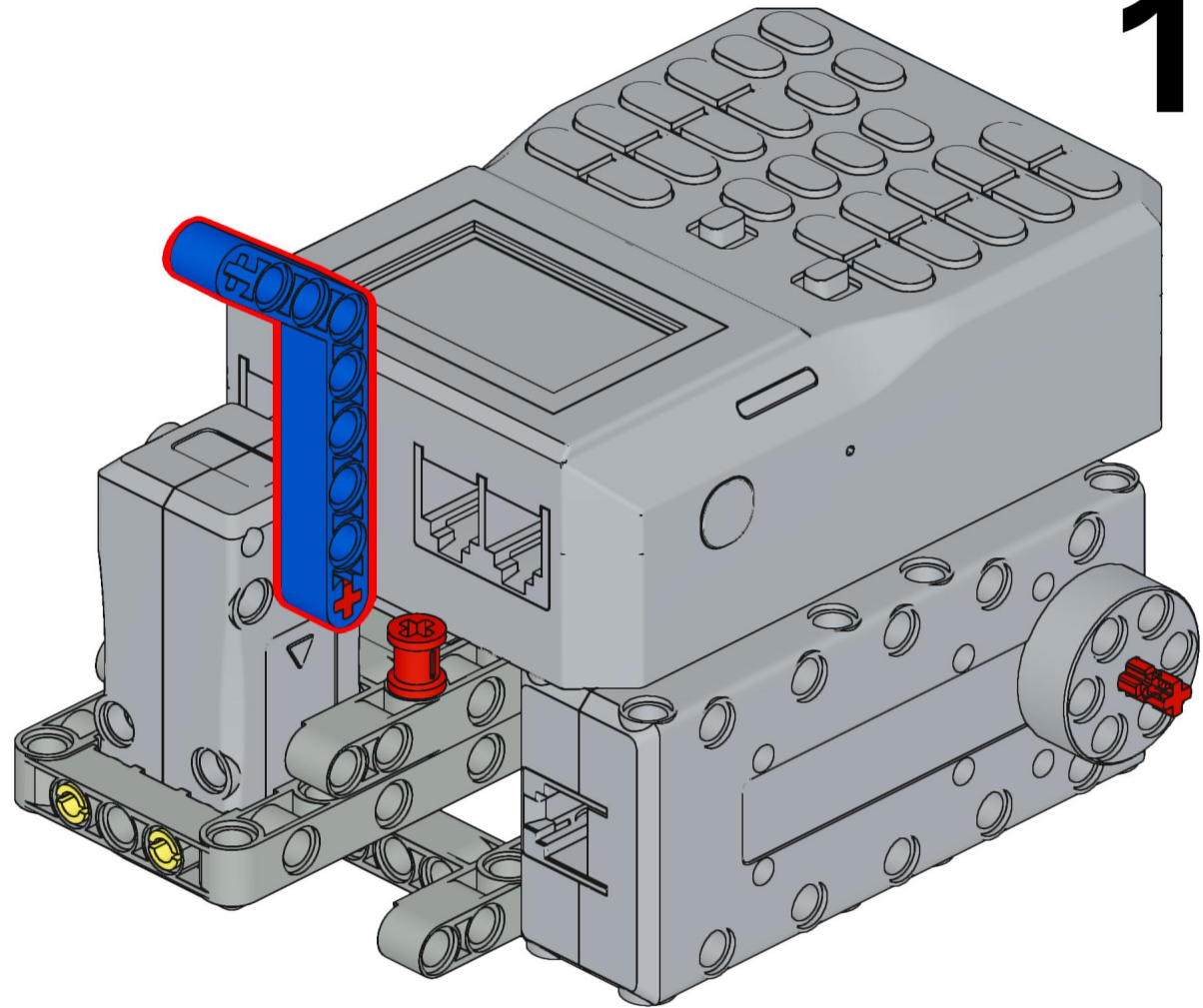


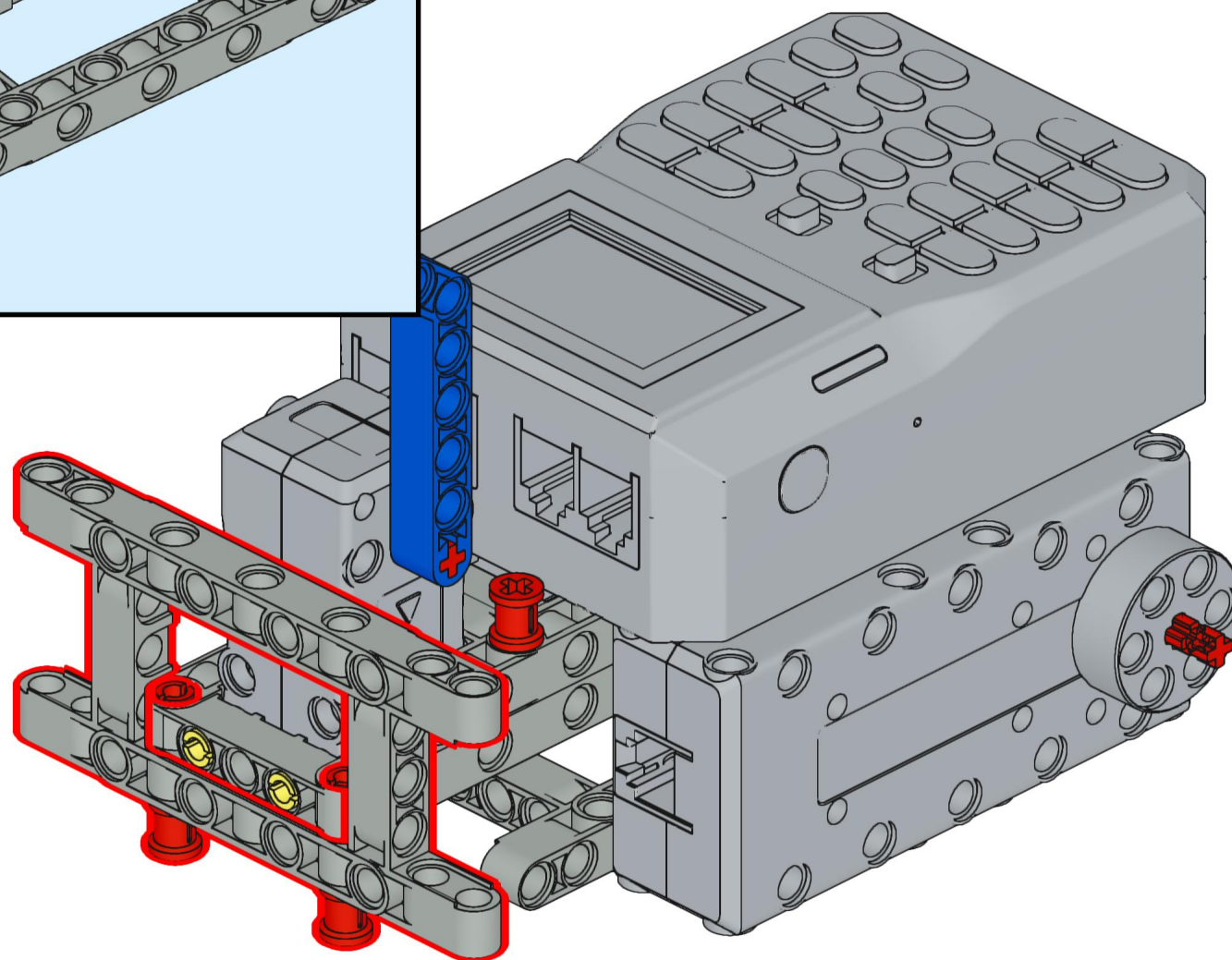
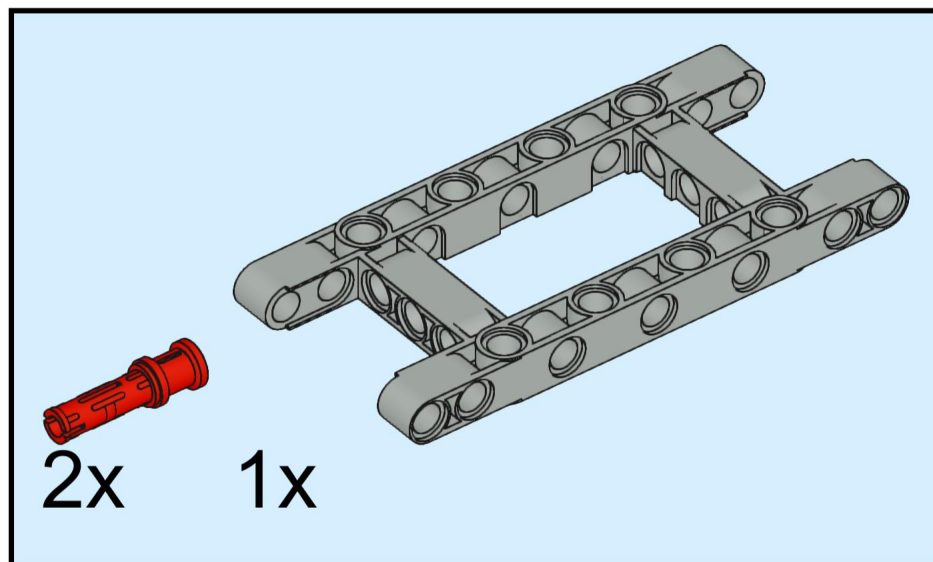
14

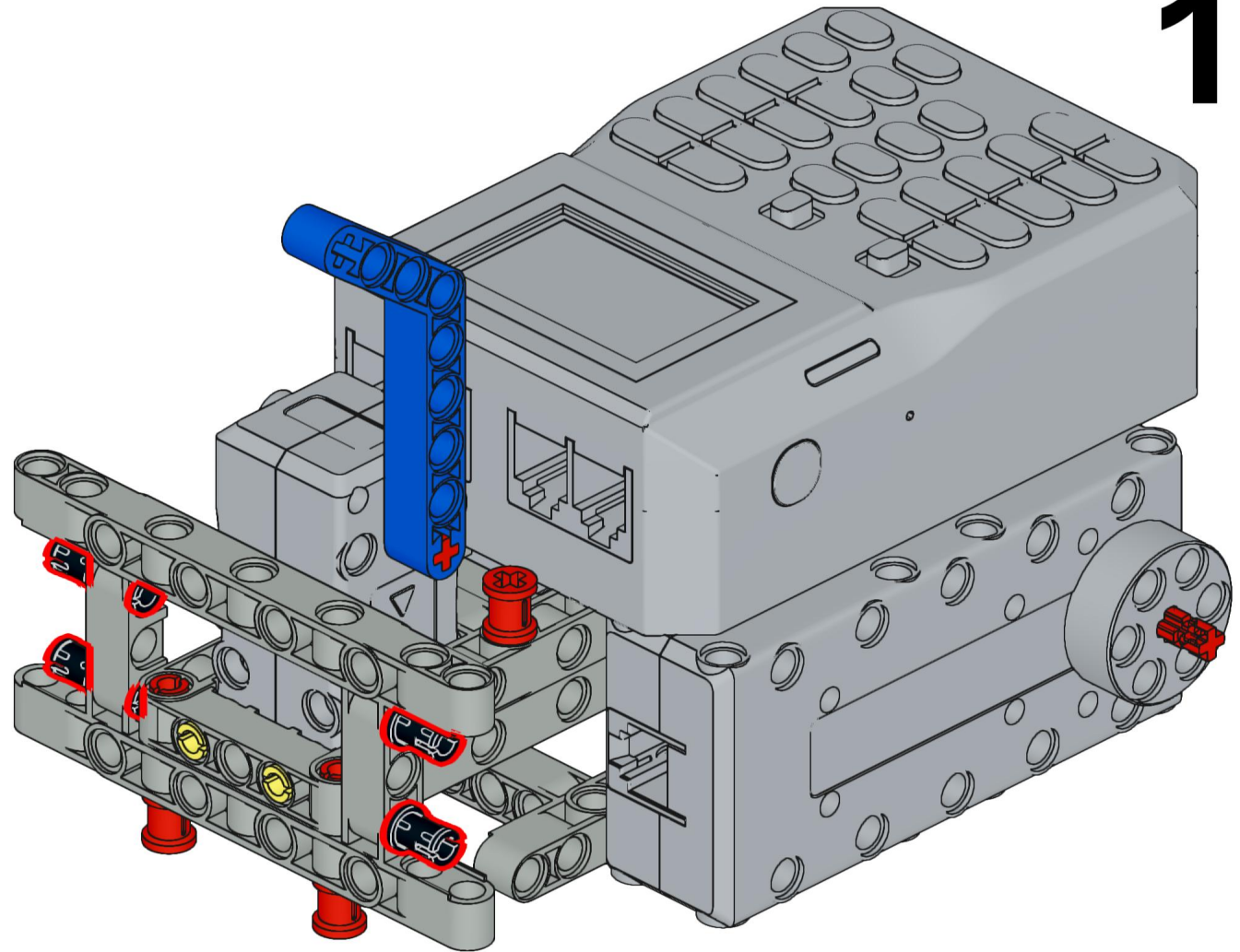


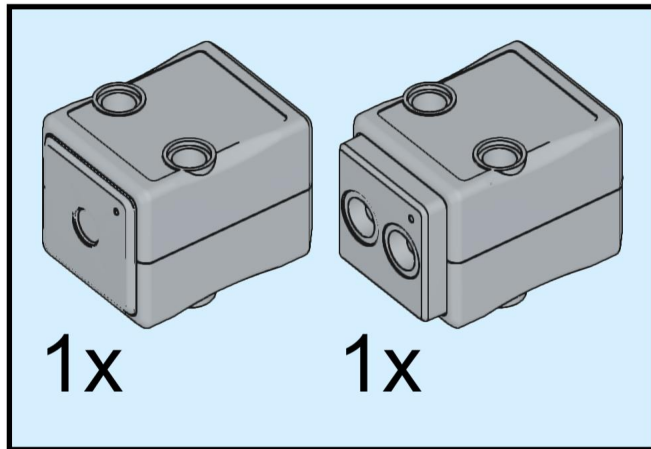


First connect the servo to the controller's C port, then set the angle to 0°, and install it at the 0° position as shown in the figure

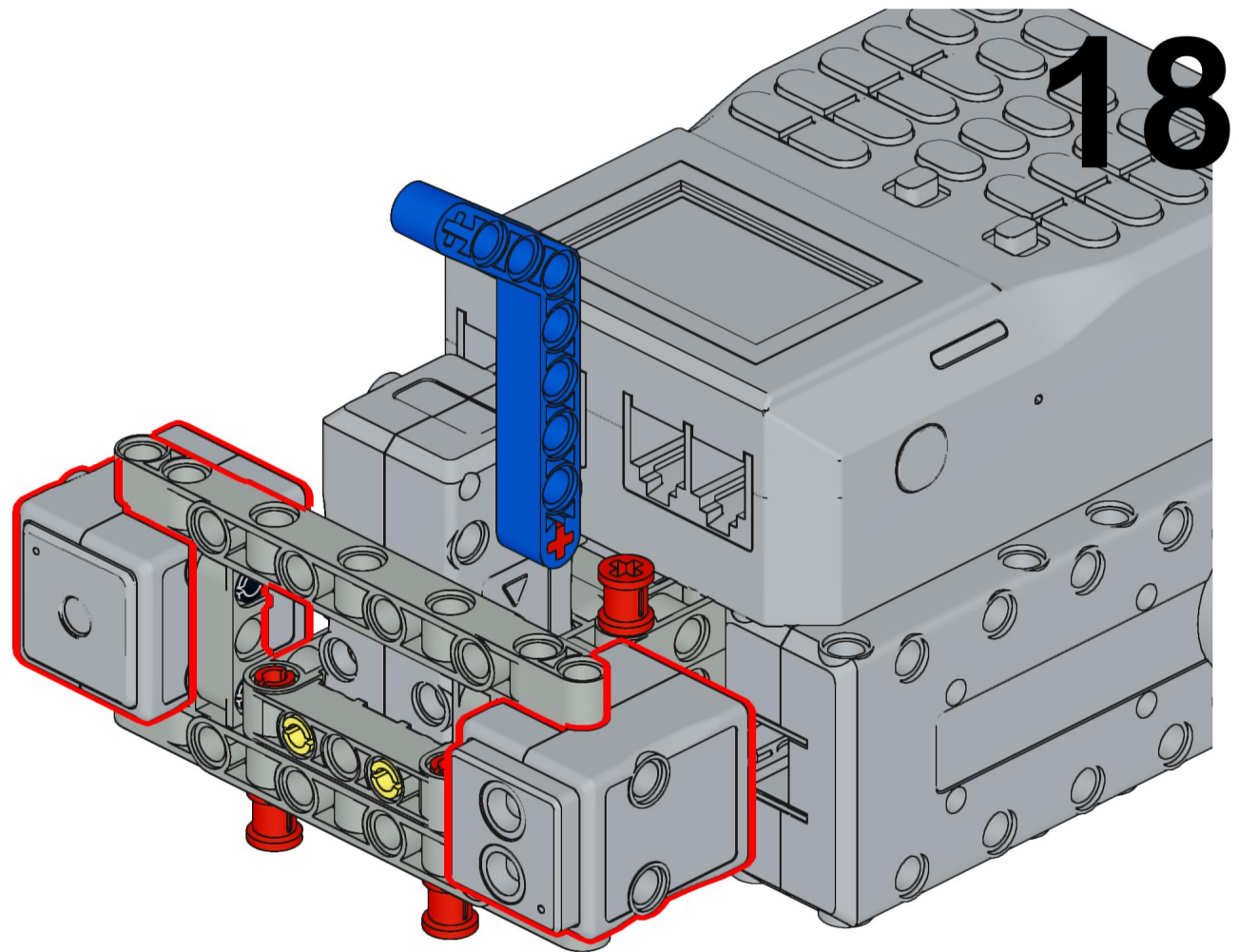




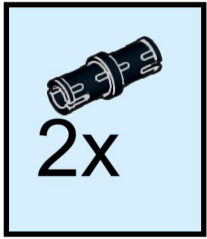




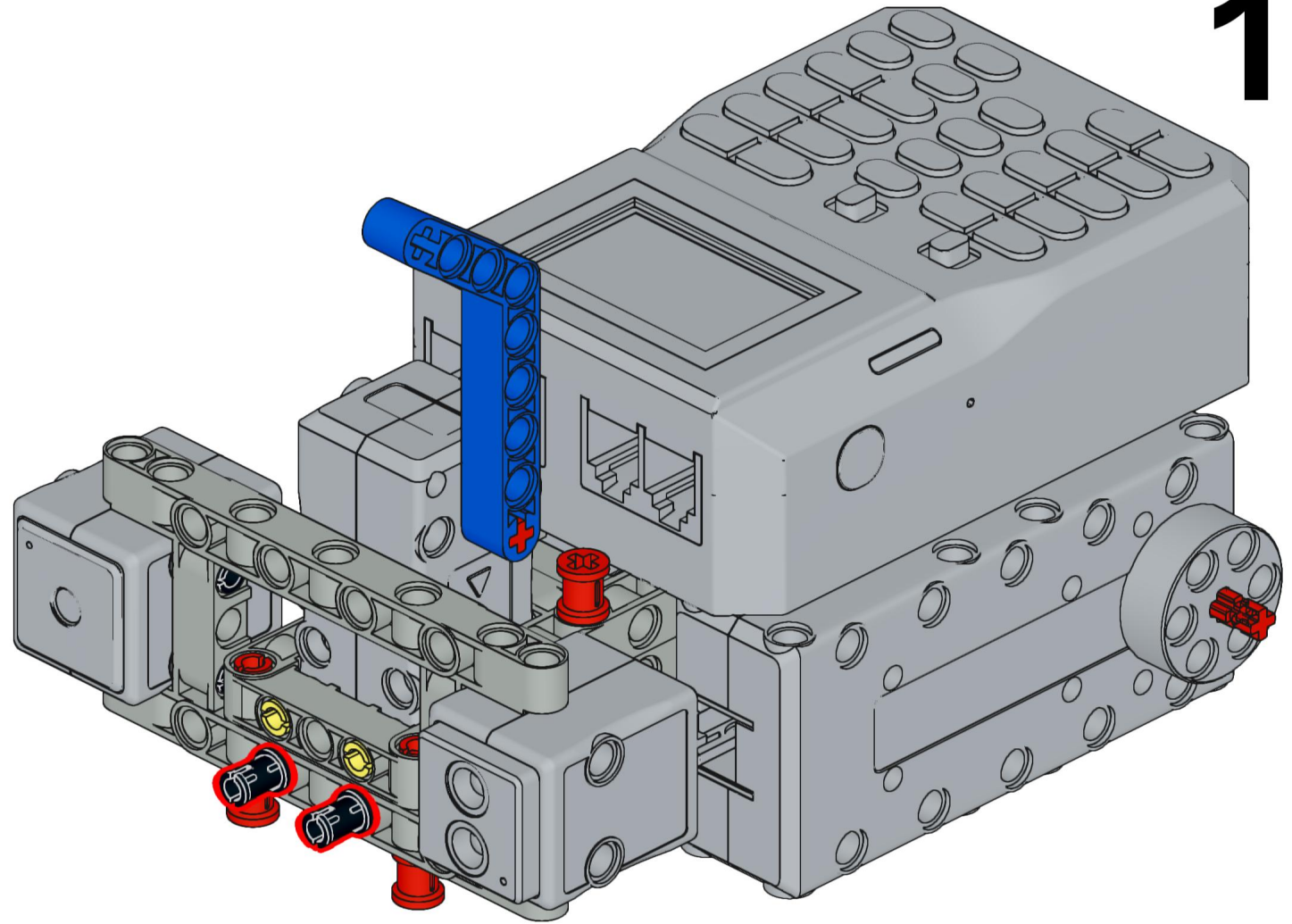
the light is connected  
to the controller's D  
port



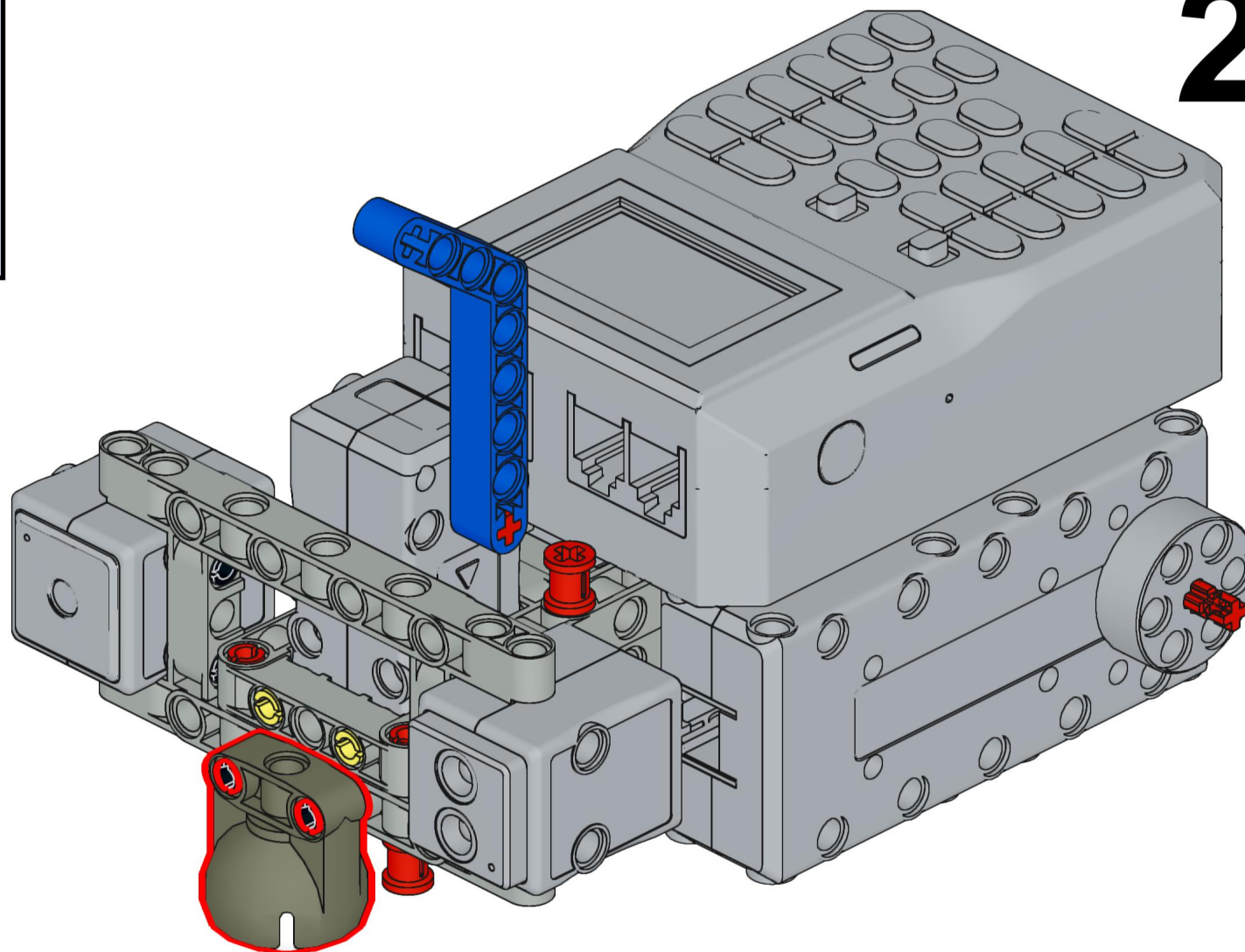
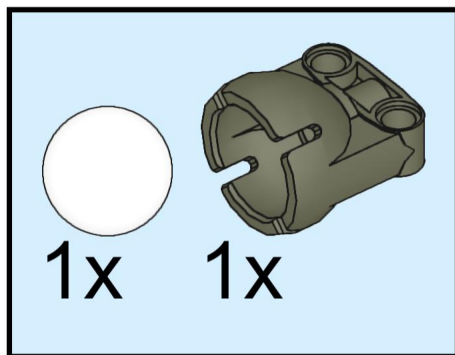
the infrared sensor is  
connected to the  
controller's E port



19



20



# 21

